

# Smart Monitoring – Data structure and Optimal Experimental Design (OED) methods for (geo)physical data acquisition

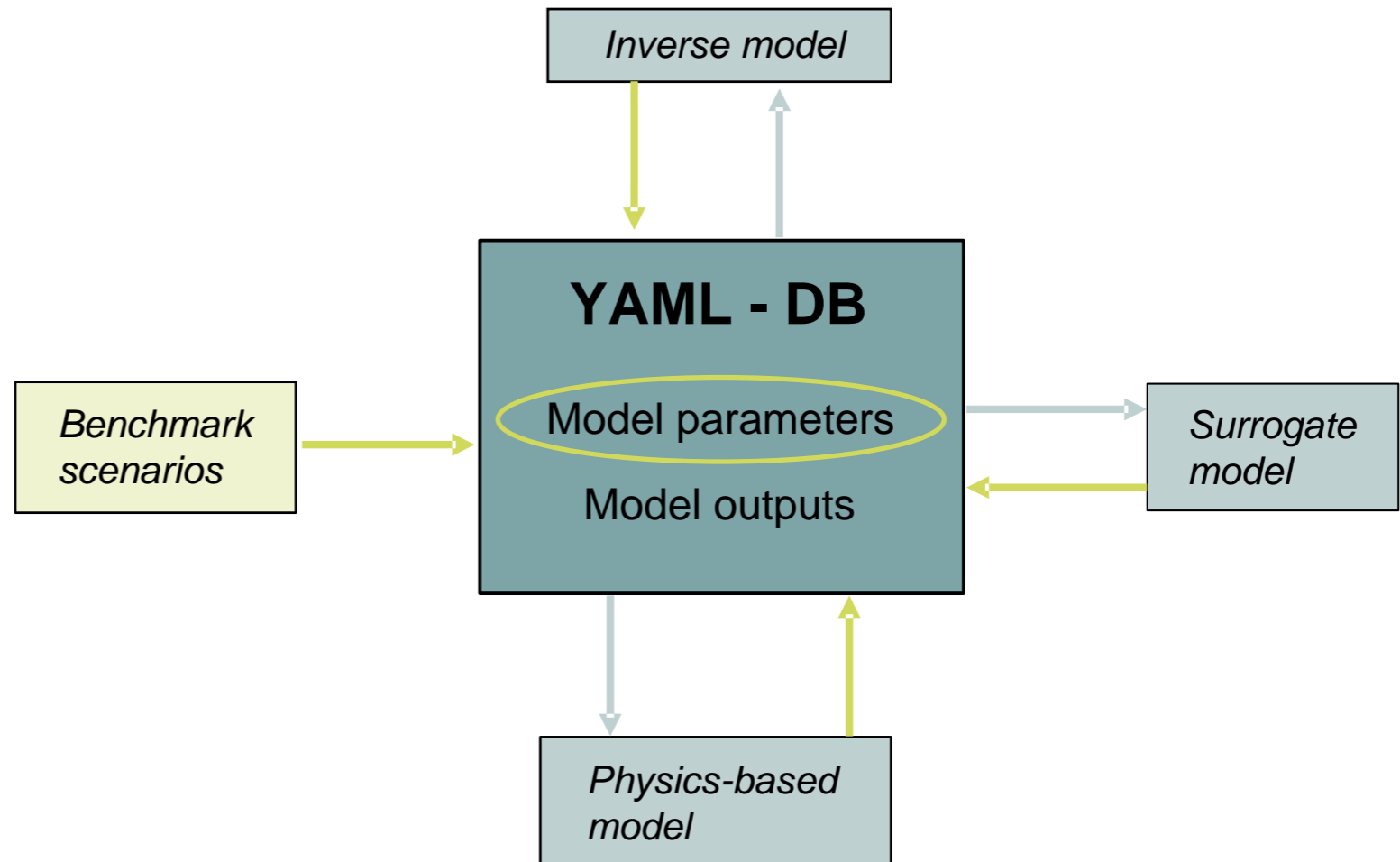
Nino Menzel

Third URS PhD workshop, Leipzig

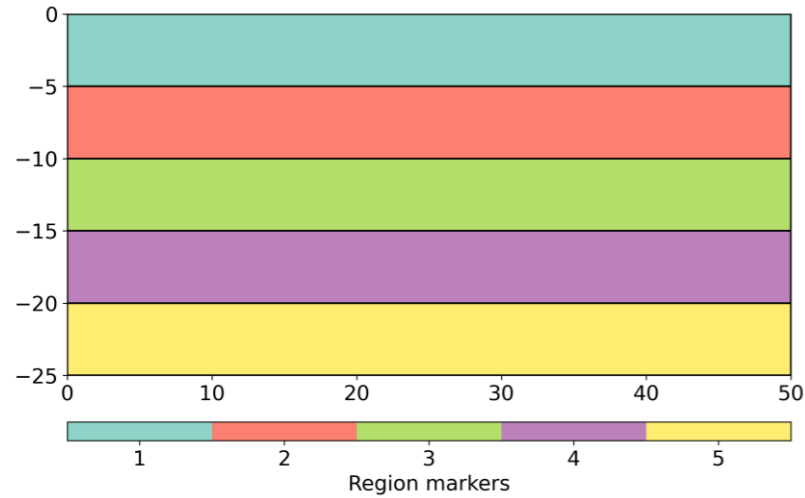
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# Data structure – Overview and recap

- Model parameters are stored as **YAML files**
- **Input:** literature and field data from benchmark scenarios
- Referenced parameters can be utilized in **process models and inversions**
- Advantage: **simple, easily accessible** storage of important model parameters



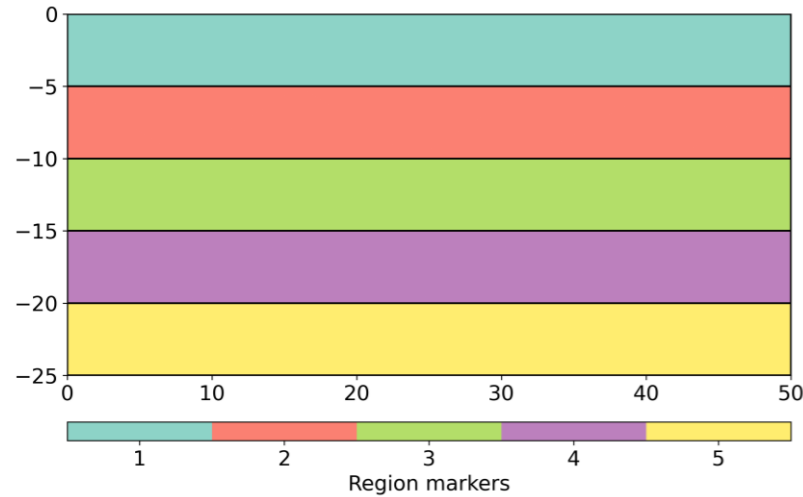
# Data structure – YAML-files



## OpalinusClay\_MontTerri.yml

- 1 Tertiary\_sandstone.yml
- 2 UpperJurassic\_sandstone.yml
- 3 MidJurassic\_Opalinus\_MontTerri.yml
- 4 LowerJurassic\_claystone.yml
- 5 Bunter\_sandstone.yml

# Data structure – YAML-files



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## MidJurassic\_Opalinus\_default.yml

- Density\_default
- Porosity\_default
- HydraulicConductivity\_default
- HeatCapacity\_default
- ElectrResistivity\_default

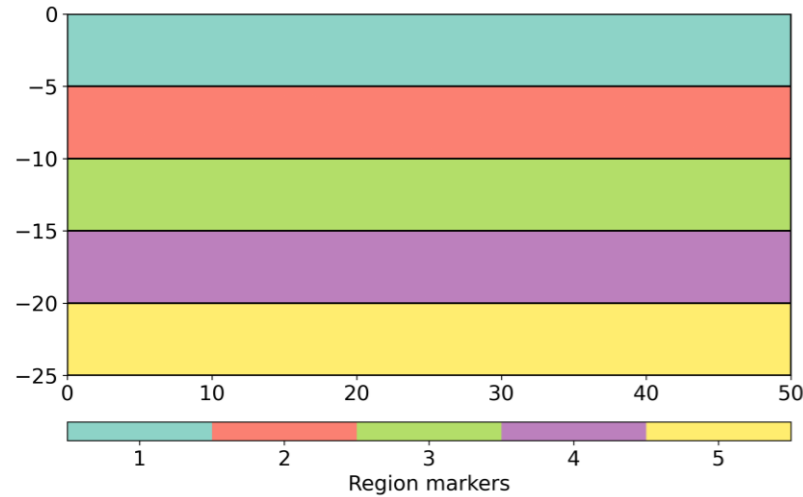
### DEFAULT VALUES

## 3 MidJurassic\_Opalinus\_MontTerri.yml

- HydraulicConductivity\_MontTerri
- ElectrResistivity\_MontTerri

### SITE SPECIFIC VALUES

# Data structure – YAML-files



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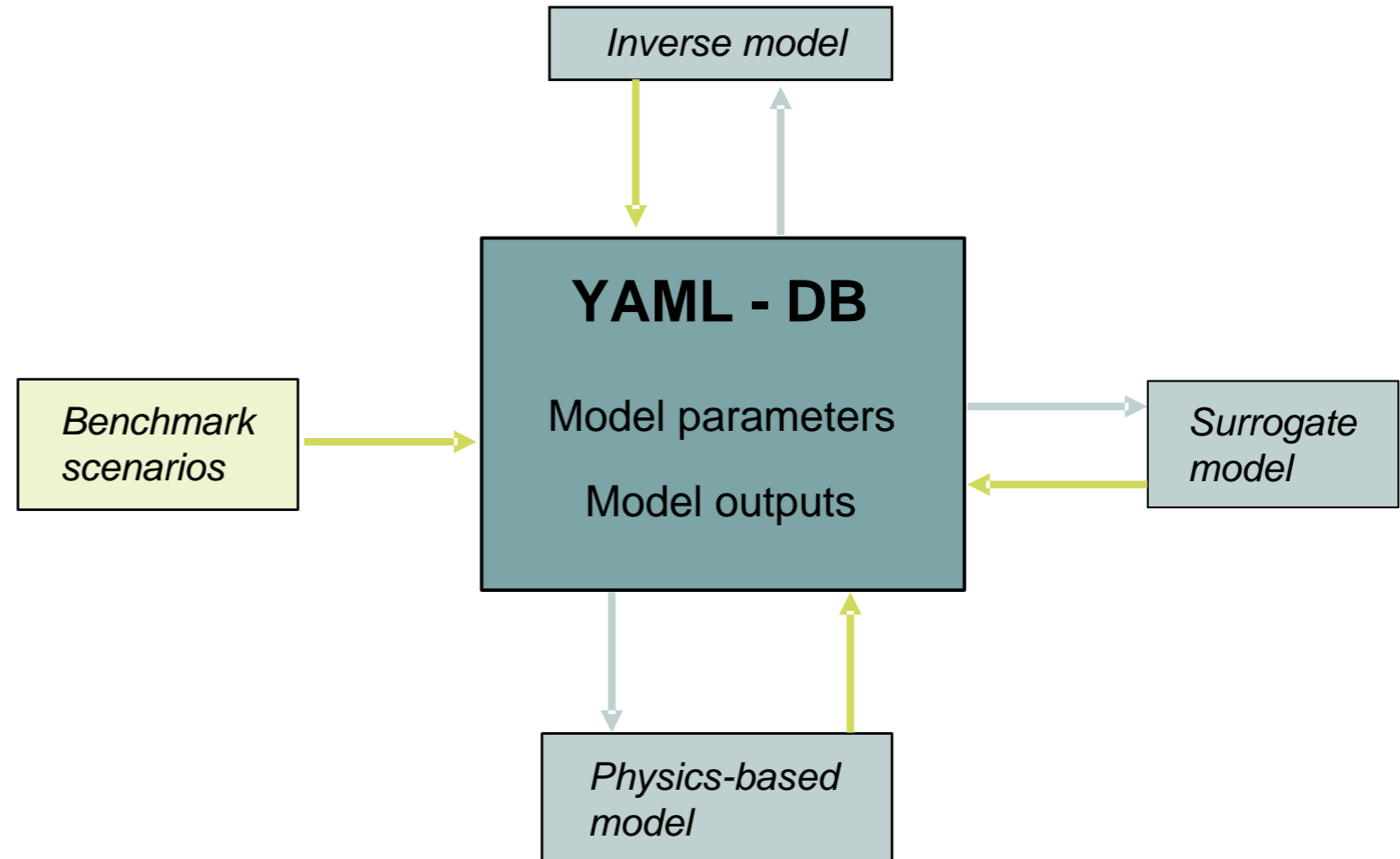
## 3 MidJurassic\_Opalinus\_MontTerri.yml

- Density\_default
- Porosity\_default
- HydraulicConductivity\_MontTerri
- HeatCapacity\_default
- ElectrResistivity\_MontTerri

## COMBINED VALUES

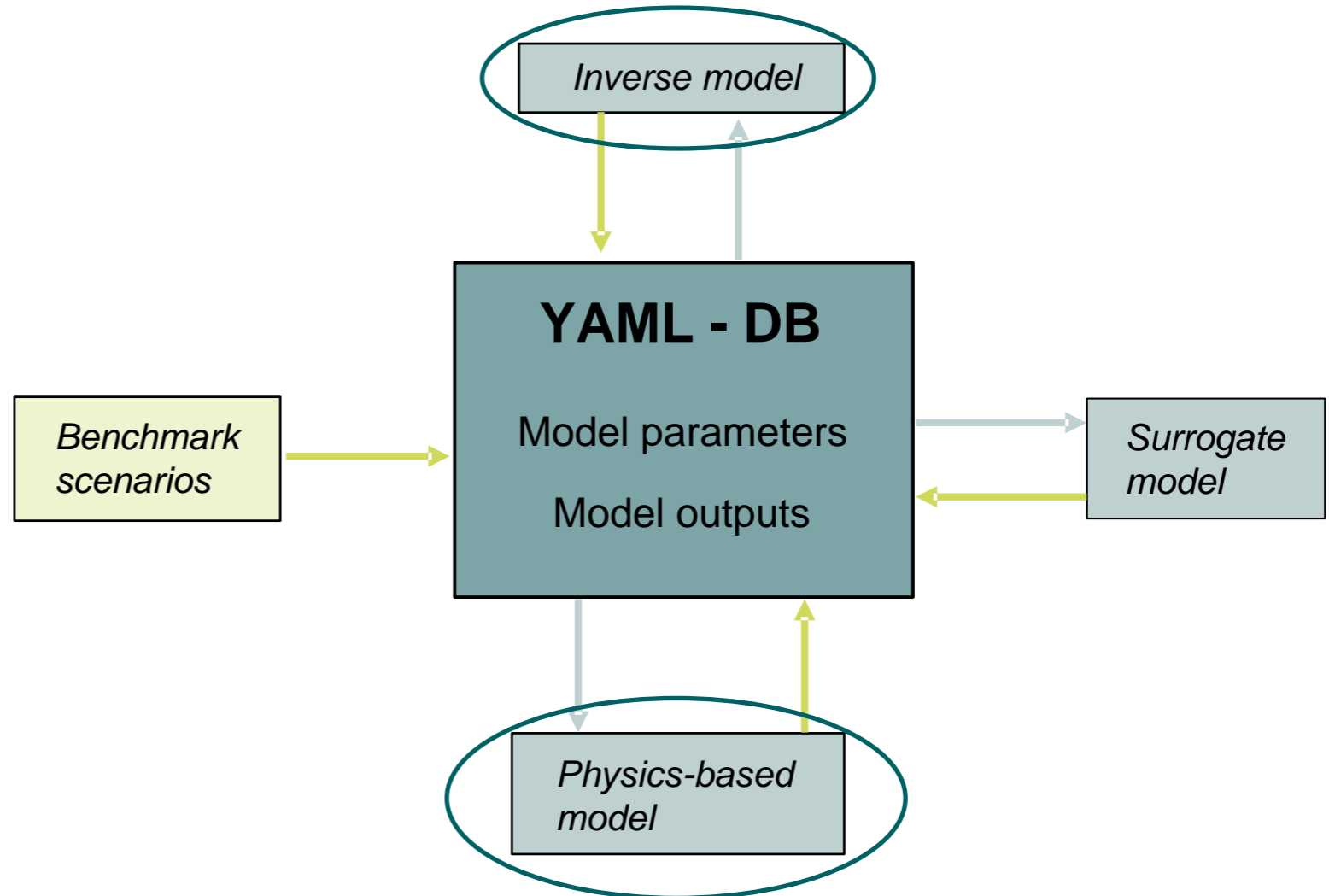
# Data structure – YAML-files

- Model parameters can be used as **input** for any kind of **simulation / model**
- **End Goal:** Library for simulation-relevant model parameters that **cover all benchmark scenarios** of possible repository sites.



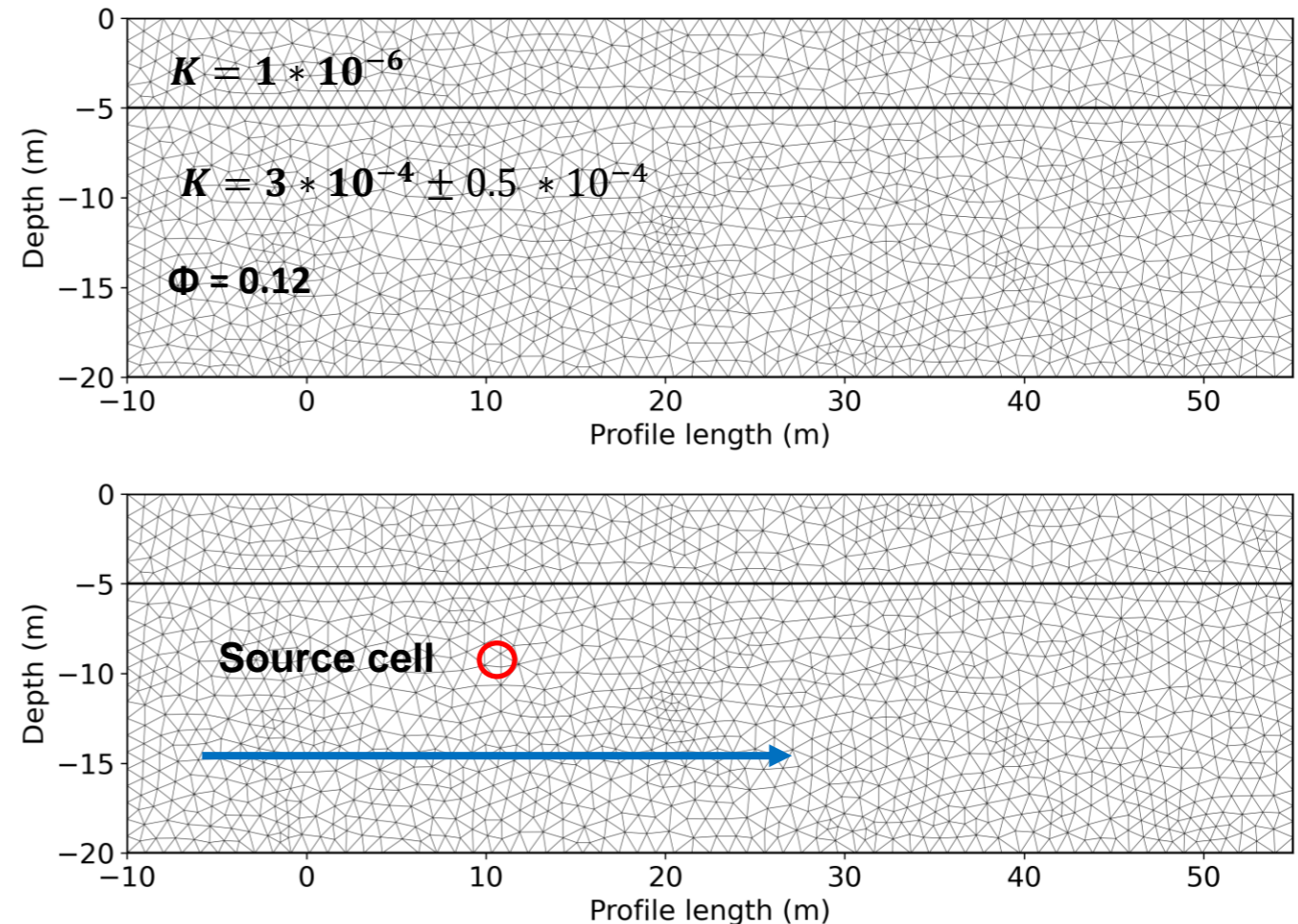
# Data structure – Integrating YAML DB into our workflow

How can we incorporate the YAML-DB into a physics-based model?



# Data structure – Integrating YAML DB into our workflow

- **2D advective-diffusive** transport simulation in a simple geometry
- **Input** parameters for simulation: **Porosity**, **Hydraulic conductivity**
- Values are **imported** from YAML-files that are stored in the **YAML-DB**
- Parameter **uncertainties** can be included by importing **deviation value** from YAML file

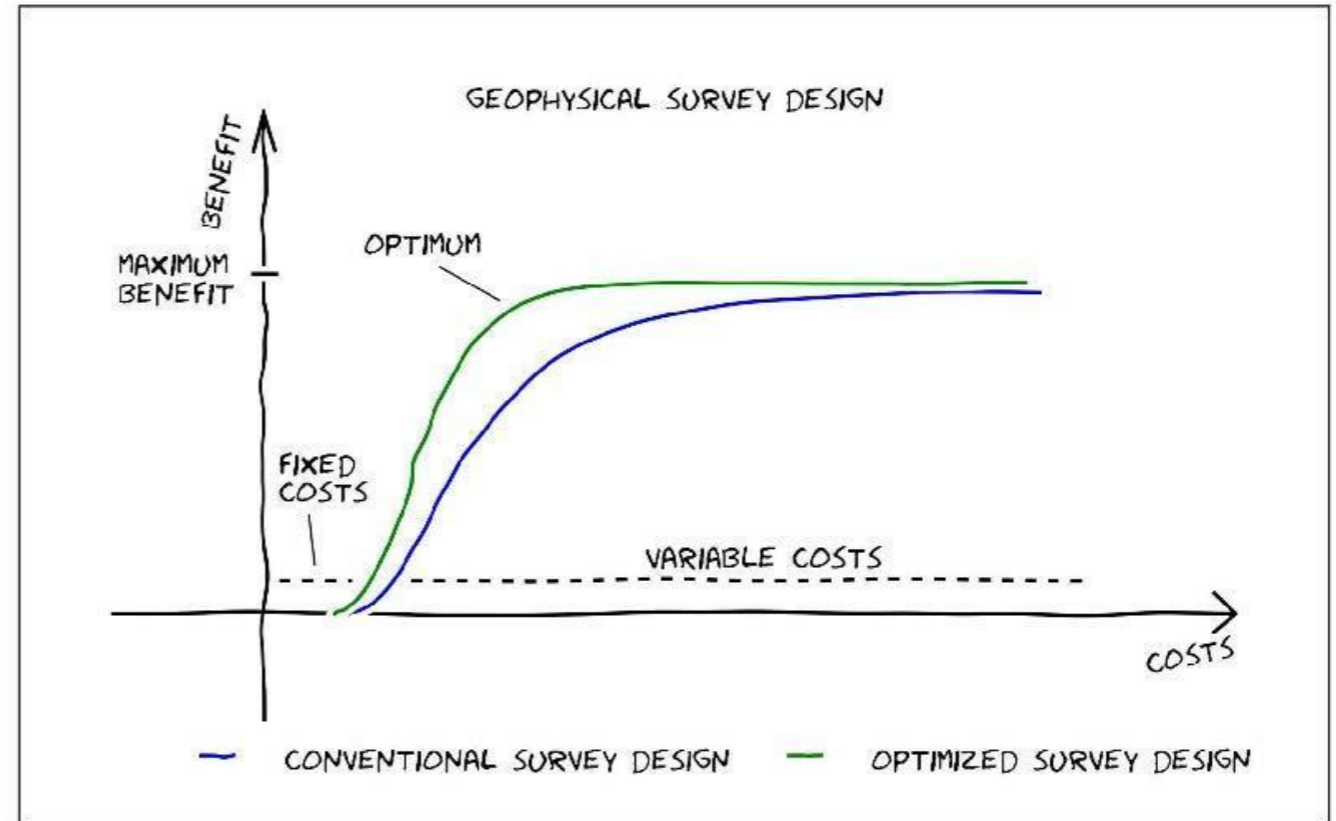




# Optimal Experimental Design - Recap

- Data processing can compensate for missing or inadequate data only to a certain extent
- Survey optimization aims at **optimizing the information content** of (geo)physical data sets while also **limiting acquisition expenses** (time and equipment)

**How can we reach the cost-benefit optimum?**



*Adapted from Maurer, 2010*

# Optimal Experimental Design - Recap

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“Compare-R” method (Wilkinson et al., 2015):

- Uses **resolution matrix** of linearized Gauss-Newton solution for ERT problem; defined as:

$$R = (G^T G + C)^{-1} G^T G$$

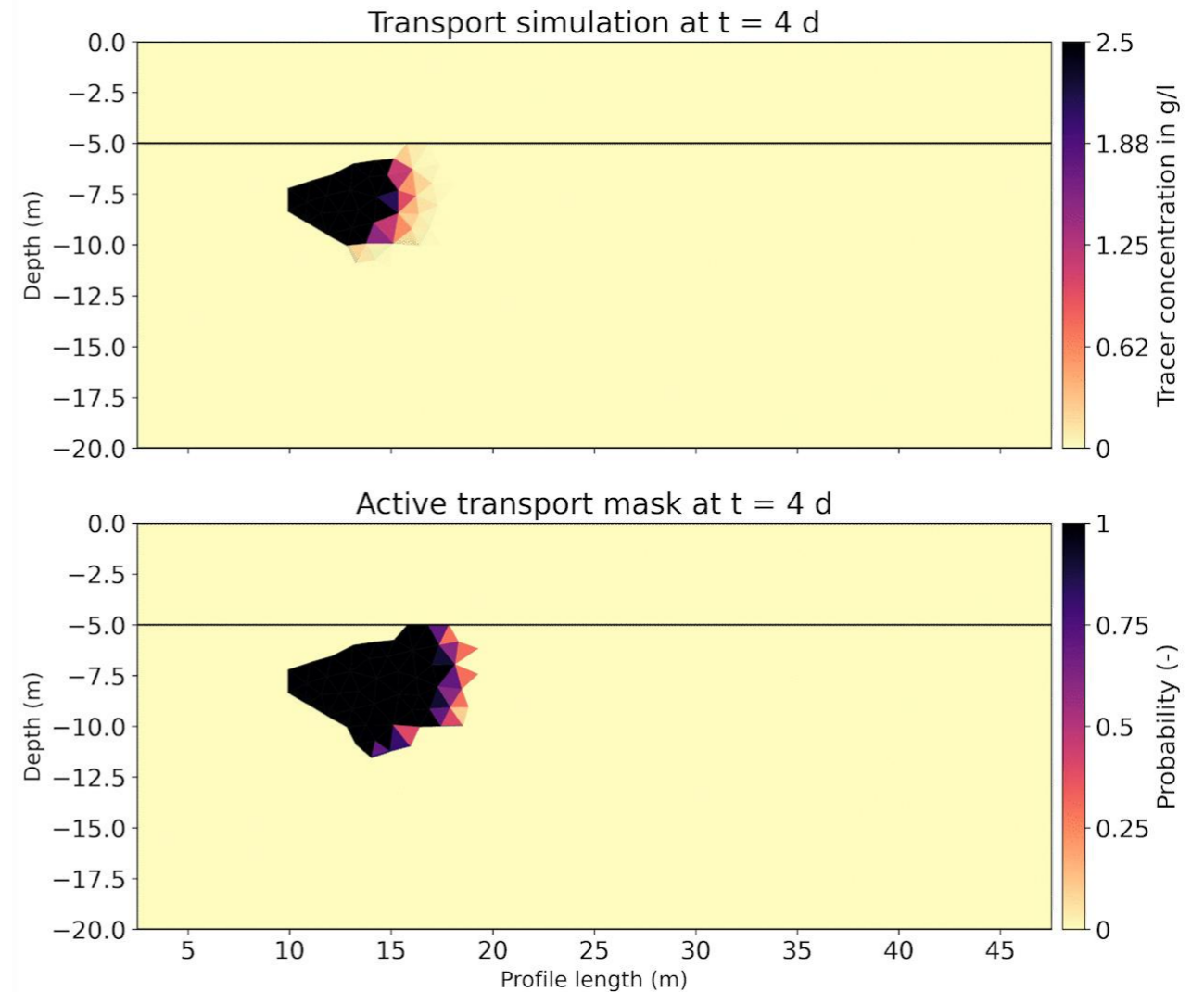
- Iterative optimization starts from a set of **base measurements** -> calculation of **change in resolution matrix** for each possible new measurement
- All additional measurements are **ranked according to improvement** of resolution matrix:

$$F_{CR} = \frac{1}{m} \sum_{j=1}^m \frac{w_{t,j} \Delta R_{b,j}}{R_{c,j}}$$

- Depending on chosen step size, **n measurements** with greatest benefit **are added to base set**

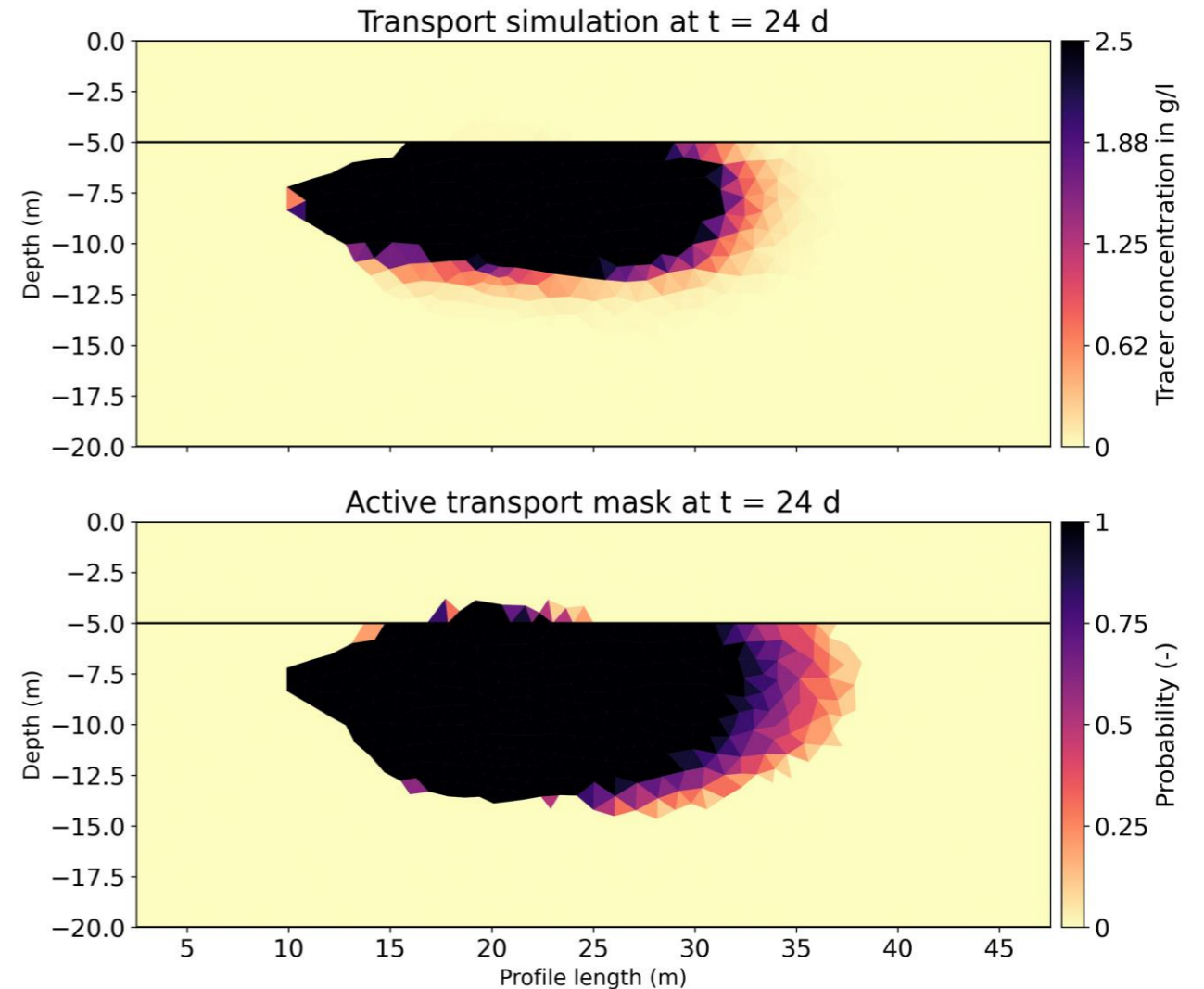
# Optimal Experimental Design – Model-driven OED

- Algorithm aims at giving “**extra resolution**” to regions that are influenced by transport process
- Underlying transport simulation is taken for creation of **focusing mask** at each time step
- If the simulated **fluid concentration** in a model cell is **above a set threshold**, it is considered “relevant”.



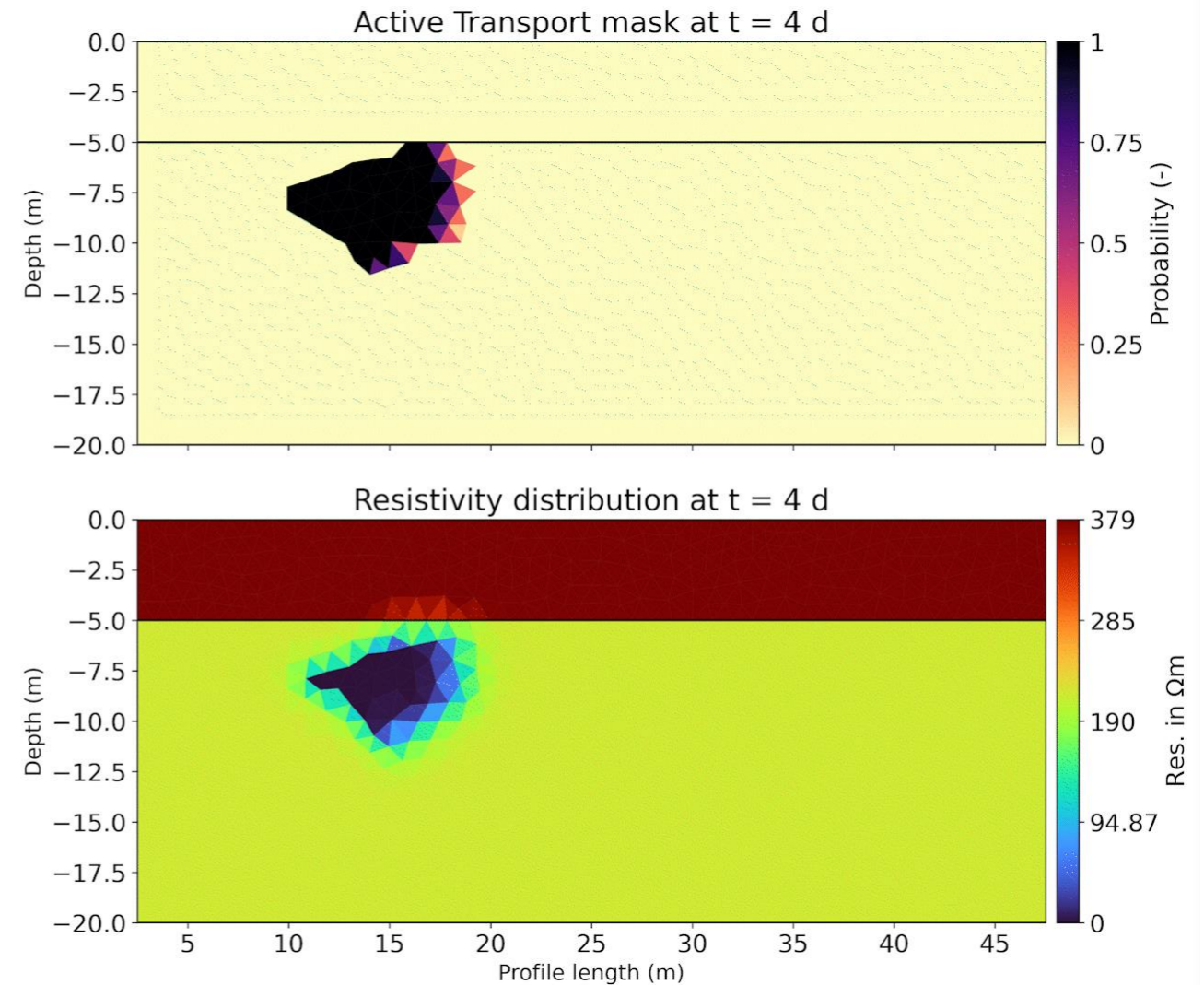
# Optimal Experimental Design – Incorporating uncertainties

- OED algorithm allows for **incorporation of uncertainties**, e.g., for hydraulic conductivity
- **Multiple simulation runs** for different **K** values in defined range
- **Value** of the cell inside the mask reflects **probability of concentration > threshold** for simulation runs with variable **K**
- Incorporated in weighting factor of **ranking function** of OED



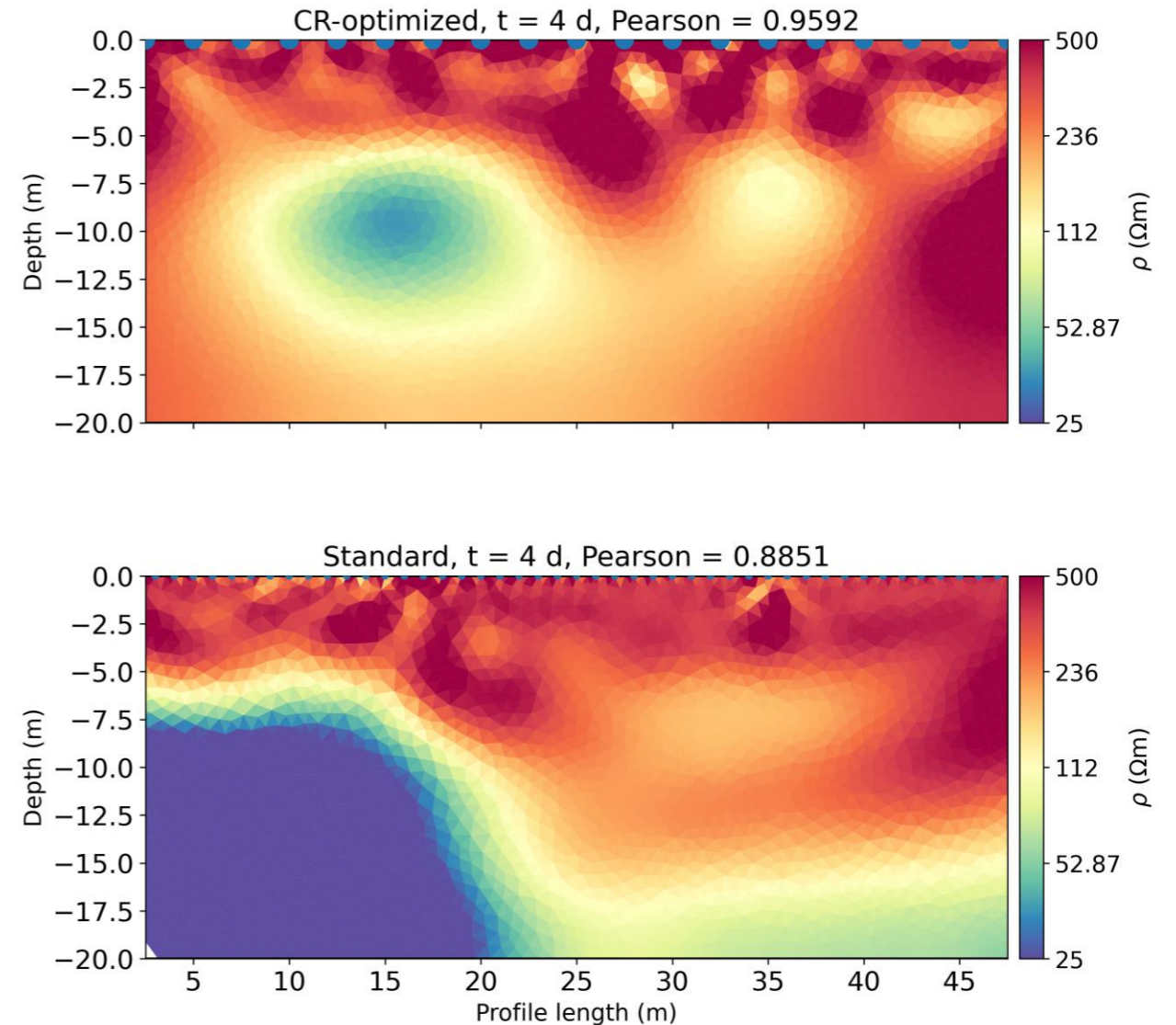
# Optimal Experimental Design – Model-driven OED

- “**Petrophysical link**” via **Archie (1943)** allows for estimation of **electrical resistivities** for a given fluid concentration
- Necessary for **geophysical** forward modelling and inversion



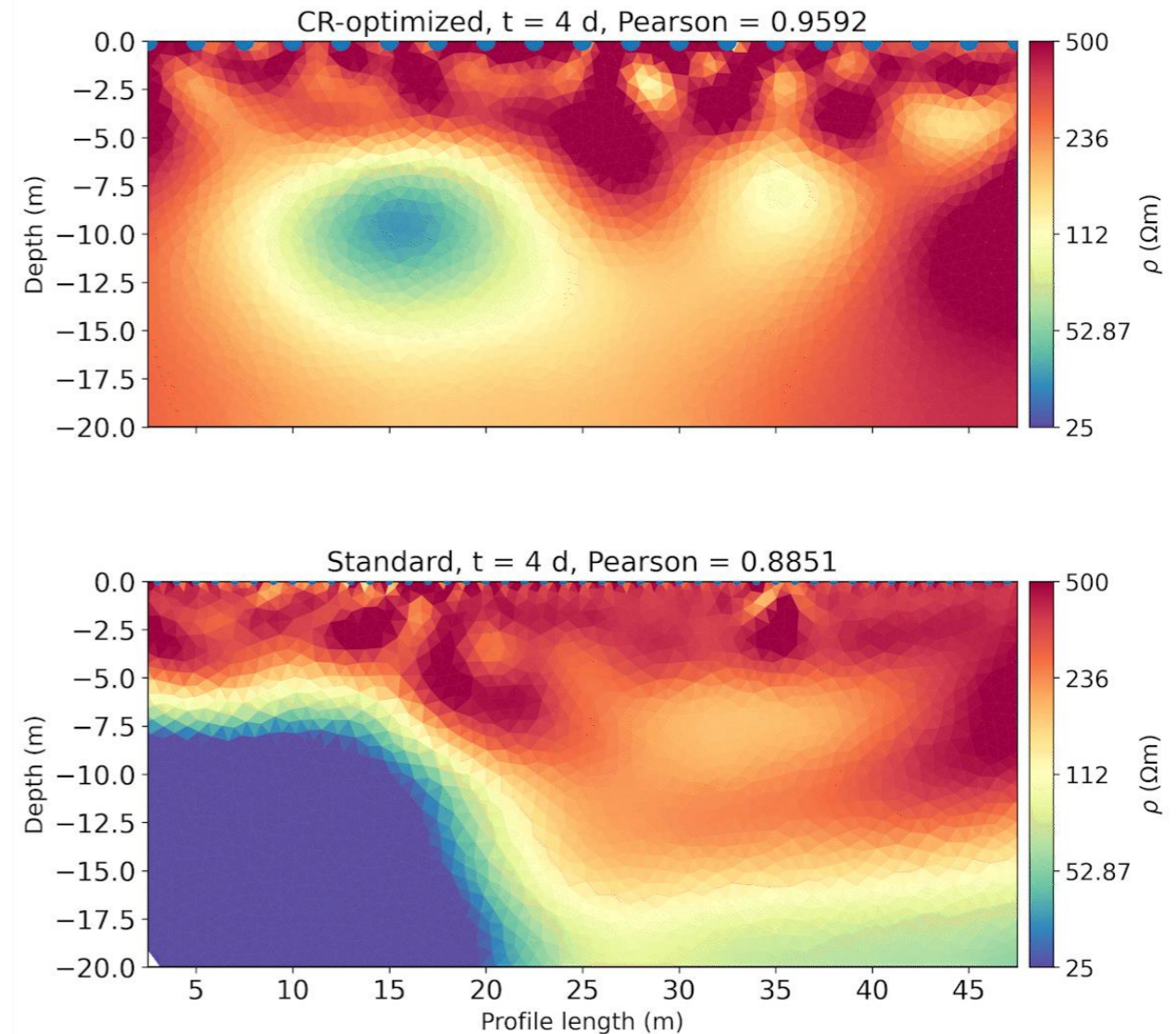
# Optimal Experimental Design – Model-driven OED

- Two geophysical surveys presented:
  1. **Optimized** dataset using **25 electrodes** and 950 measurement points
  2. **Standard** Dipole-Dipole configuration using **50 electrodes** and > 1100 measurements
  
- **More electrodes -> more costs**



# Optimal Experimental Design – Model-driven OED

- Created **probability mask** is used in OED algorithm: gives **extra resolution** to masked area with **significant fluid concentrations**
  - Allows **focusing** of measurements to **relevant areas** of model domain
- > We aim at **optimizing the information content** of (geo)physical data sets while also **limiting acquisition expenses** (time and equipment)



# Smart Monitoring – Outlook and next steps

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## Data management:

- Continue with literature research and **fill YAML-DB**
- **Unify** existing YAML files and datasets and **integrate** them into our workflows

## Optimal Experimental Design:

- **Implement data-driven OED** and compare to model-driven approach (idea of hybrid OED algorithm?)
- Adapt OED to **other (geo)physical parameters** and optimize datasets for **joint inversions**



# Thanks for your attention!

## LITERATURE:

ARCHIE, G. E. (1942). The electrical resistivity log as an aid in determining some reservoir characteristics. *Transactions of the AIME*, 146(01), 54-62.

MAURER, H., CURTIS, A., & BOERNER, D. E. (2010). Recent advances in optimized geophysical survey design. *Geophysics*, 75(5), 177-194.  
<https://doi.org/10.1190/1.3484194>

WILKINSON, P. B., UHLEMANN, S., MELDRUM, P. I., CHAMBERS, J. E., CARRIÈRE, S., OXBY, L. S., & LOKE, M. H. (2015). Adaptive time-lapse optimized survey design for electrical resistivity tomography monitoring. *Geophysical Journal International*, 203(1), 755–766. <https://doi.org/10.1093/gji/ggv329>

# Optimal Experimental Design – Application to transport processes

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## Data driven active OED:

Makes use of **the acquired data** at a certain time **to focus** the survey on the region of the model where changes occur.

## Model driven active OED:

Utilizes an **underlying transport simulation** to focus the measurements on the region of the model that shows **transport-induced changes**.

# Optimal Experimental Design - Recap

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**Compare-R'' method** (Wilkinson et al., 2015):

- Uses **resolution matrix** of linearized Gauss-Newton solution for ERT problem; defined as:

$$R = (G^T G + C)^{-1} G^T G$$

- Iterative optimization starts from a set of **base measurements** -> calculation of **change in resolution matrix** for each possible new measurement:

$$\Delta R_b = \frac{z}{1+(g*z)} (g^T - y^T) \quad \text{where} \quad z = (G_b^T g_b + C)^{-1} g, \quad y = (G_b^T G_b) z$$

- All additional measurements are **ranked according to improvement** of resolution matrix:

$$F_{CR} = \frac{1}{m} \sum_{j=1}^m \frac{w_{t,j} \Delta R_{b,j}}{R_{c,j}}$$

- Depending on chosen step size, **n measurements** with greatest benefit **are added to base set**