# Uncertainty-Informed, Surrogate-Assisted Bayesian Optimized Experimental Design for Fluid Transport Process Monitoring

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## 1) Motivation

**Enhancing the efficiency of geophysical surveys** by performing Optimized Experimental Design (OED) is of **high importance** for field surveys, especially in highly **sensitive environments**.

However, one particular challenge in OED for fluid transport process monitoring is the **limitation of computational expenses** in both the underlying transport models as well as the OED step.

We present a **robust, surrogate-assisted Bayesian Optimized Experimental Design strategy** for geophysical field measurements, that...

- provides an efficient stochastic alternative to deterministic OED approaches for dynamic targets, such as the Compare-R approach (e.g., Wilkinson et al., 2015)
- aims at considering parameter uncertainties by introducing uncertainty-informed transport models for the optimization process
- uses surrogate models (emulators) to reduce the computational burden associated to the forward model

## 2) Bayesian optimization algorithm

The **Bayesian experimental design method** (Qiang et al., 2022) is based on the **Bayes** formulation of the geoelectrical inverse problem, written as:

 $p(\mathbf{m}) p(\mathbf{d} | \mathbf{m}, \mathbf{s})$ 

## 3) Surrogate-assisted approach

For a Bayesian OED approach, we need a **large number of model runs** to obtain representative masks and uncertainty estimators **——** computationally expensive

We aim to substitute the computationally expensive forward model with a surrogate model which

$$p(\boldsymbol{m}|\boldsymbol{d},\boldsymbol{s}) = \frac{p(\boldsymbol{m})p(\boldsymbol{d}|\boldsymbol{n},\boldsymbol{s})}{p(\boldsymbol{d}|\boldsymbol{s})}$$

where p(m) is the **prior density** of model parameters m and p(m|d, s) is the **posterior density** of m. p(d|m, s) is the **likelihood function**, which is a **joint probability distribution** of measurements d and model parameters m. p(d|s) is the **Bayesian evidence factor**.

The difference between prior and posterior is caused by the measurements d and quantified by the Kullback-Leibler divergence U(s):

$$U(s) = \frac{1}{n} \sum_{i=1}^{n} \{ \ln[p(\boldsymbol{d}^{i} | \boldsymbol{m}^{i}, \boldsymbol{s})] - \ln[p(\boldsymbol{d}^{i} | \boldsymbol{s})] \}$$

where *m<sup>i</sup>* is the randomly generated MC samples with prior information of the model parameters m.



- is trained on **input-output data pairs** from the full model
- runs in a **fraction of the time**



#### Surrogate model

Back transform to original output size

**Research question:** Which **surrogate + dimension reduction** approach reduces the associated error and fits the problem best? How to include the surrogate + DR error in OED algorithm?

**Goal**: use the surrogate to generate N<sub>MC</sub> runs for Bayesian OED methodology, taking into consideration the error associated to surrogate output  $(\tilde{y}_x)$ 

## 4) Results of the synthetic study

#### Model Setup

- We consider **2 uncertain parameters**:
  - hydraulic conductivity (*K*):  $U[1x10^{-4} 3x10^{-4}]$
  - porosity (Φ): *U*[0.2, 0.5]
- Simulation of a contaminant transport in sedimentary rock (vague information on lithology / compaction)
- Contaminant is **released during a short timeframe** (quasi-instantaneous contaminant release)



#### **OED** considerations

**Fig. 1:** Comparison of the full model (upper row, left) and the surrogate (lower row, left) as well as the optimized electrical resistivity tomography (ERT) dataset using 1000 four-point configurations (middle plots in both rows). The left images show the inversion results of both the full model-based as well as the surrogate-based optimized datasets. The plot nicely visualizes the excellent performance of the surrogate in comparison to the full model, since both allow for precise focusing of the survey to the relevant model area and thus for detailed monitoring of the simulated transport process.

 We use N<sub>MC</sub> model runs to generate a mask of the area of interest based on the probability of each cell being affected: stochastic approach

#### Surrogate model considerations

- We use **Principal Component Analysis** (PCA) to reduce the output field to a smaller latent space  $(\hat{z})$
- We use a Gaussian Process Regression (GPR) as a surrogate, trained with 50 model runs.

#### 5) Outlook

- Test and compare different Bayesian OED criteria
- Apply **cell-wise probabilities** instead of mask-averaged distributions to sample from **m**
- Implement surrogate-assisted Bayesian inference on available ERT measurements to reduce uncertainty
  associated with future time step simulations for OED purposes

#### **REFERENCES**:

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